

Fig. 1

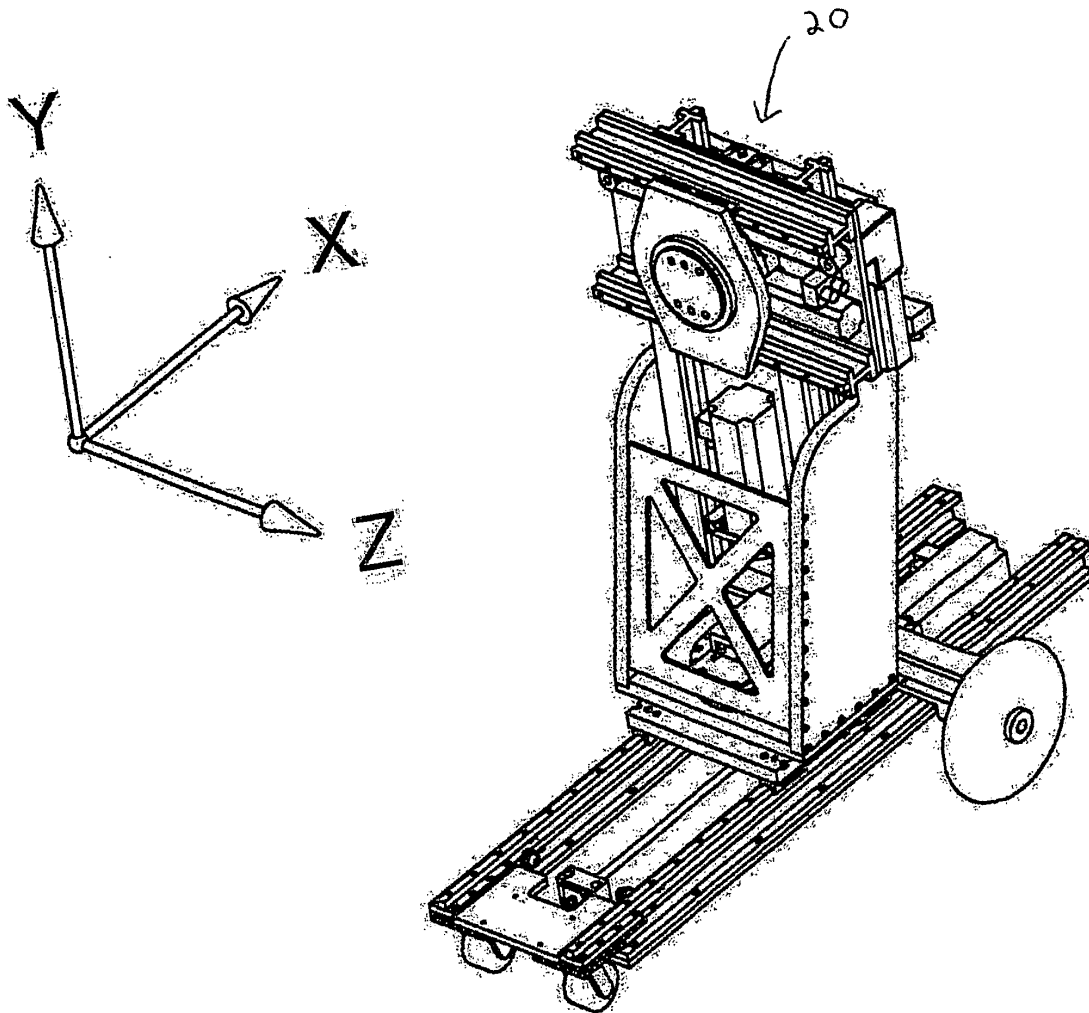


Fig. 2

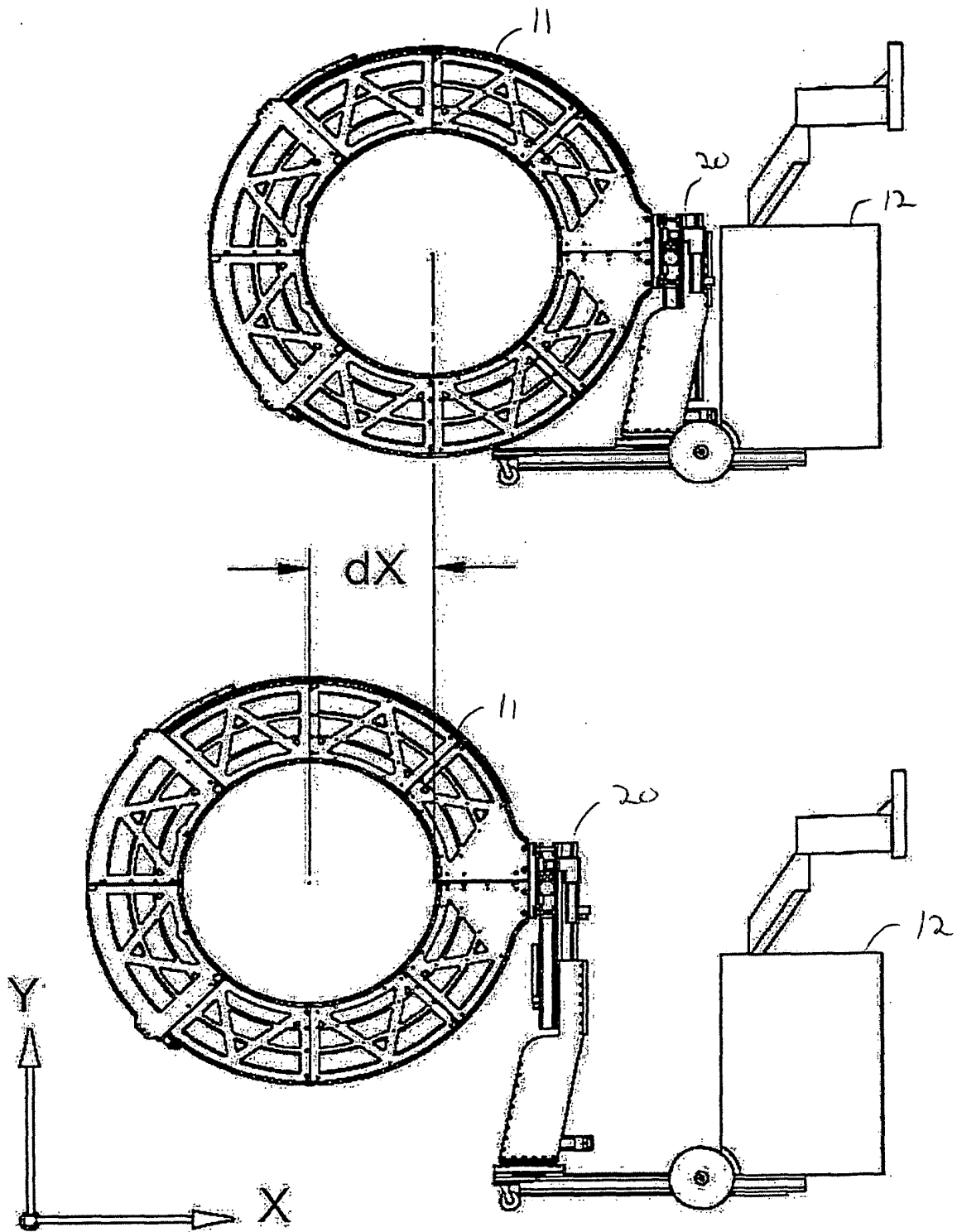


Fig. 3

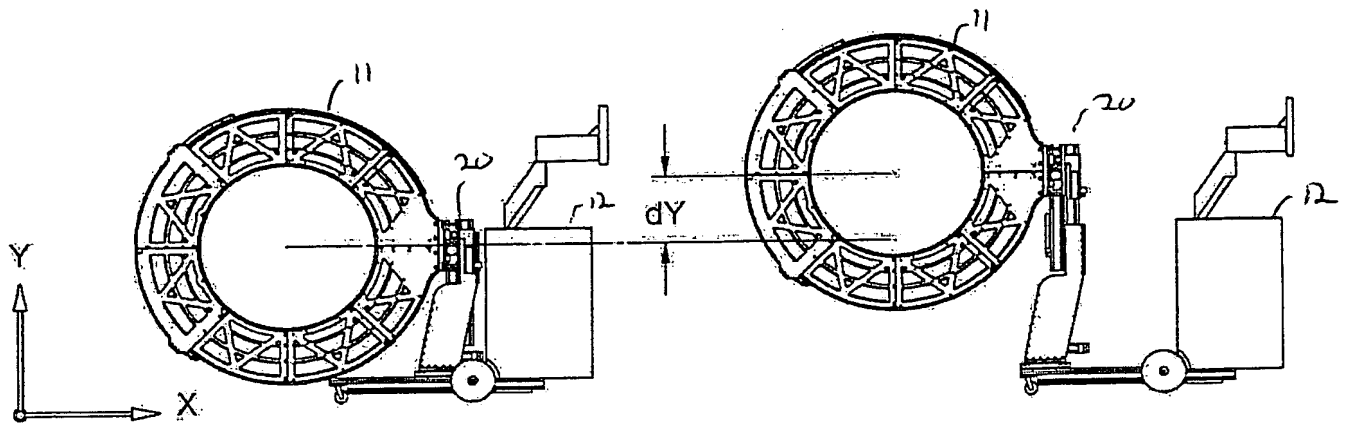


Fig. 4

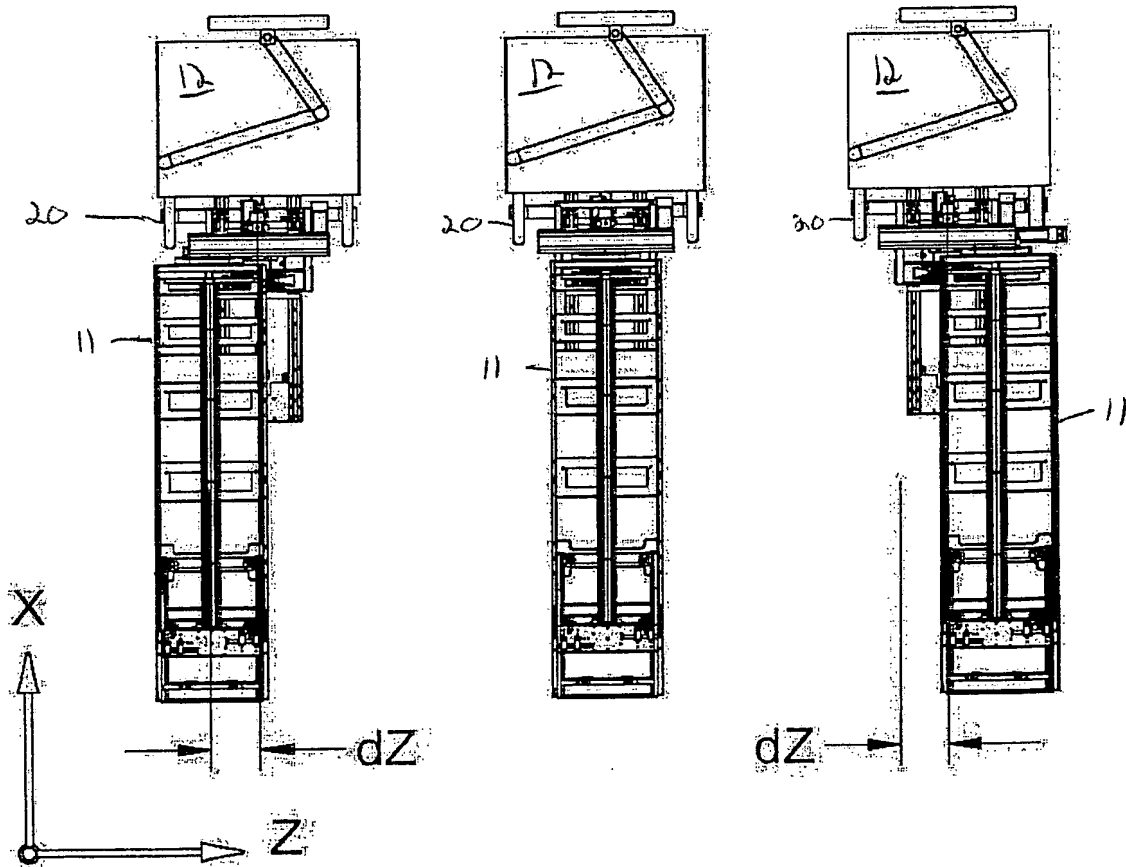


Fig. 5A

Fig. 5B

Fig. 5C

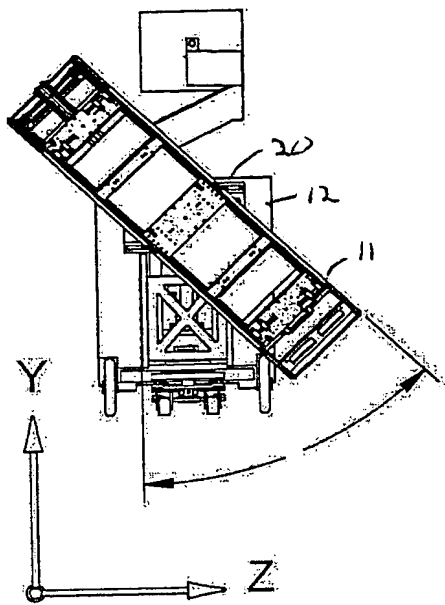


Fig. 6A

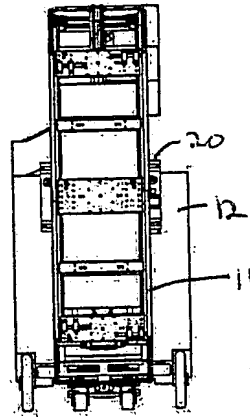


Fig. 6B

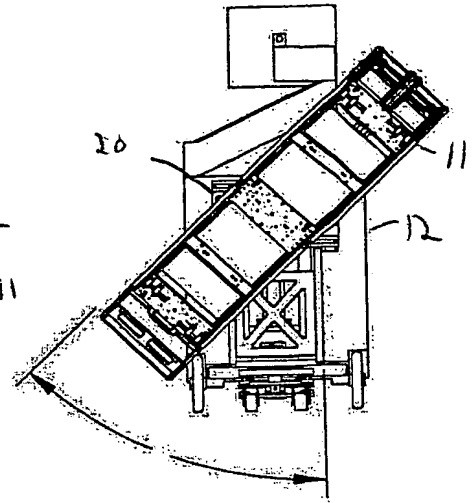


Fig. 6C

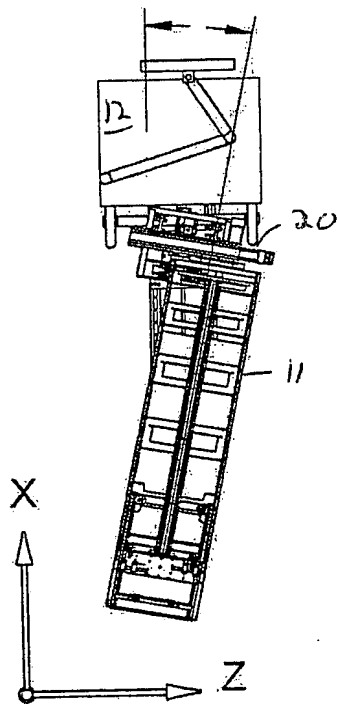


Fig. 7A

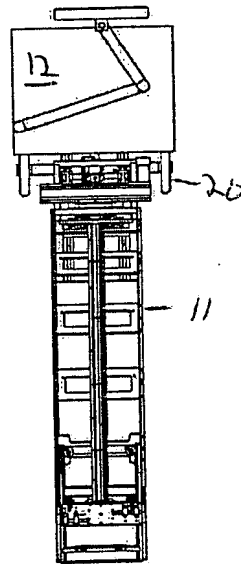


Fig. 7B

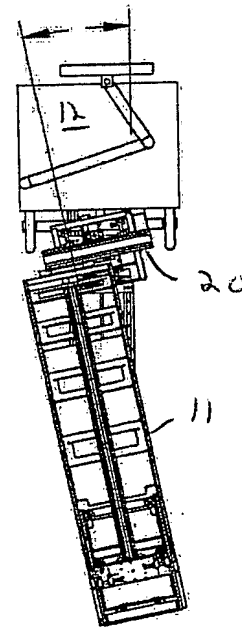
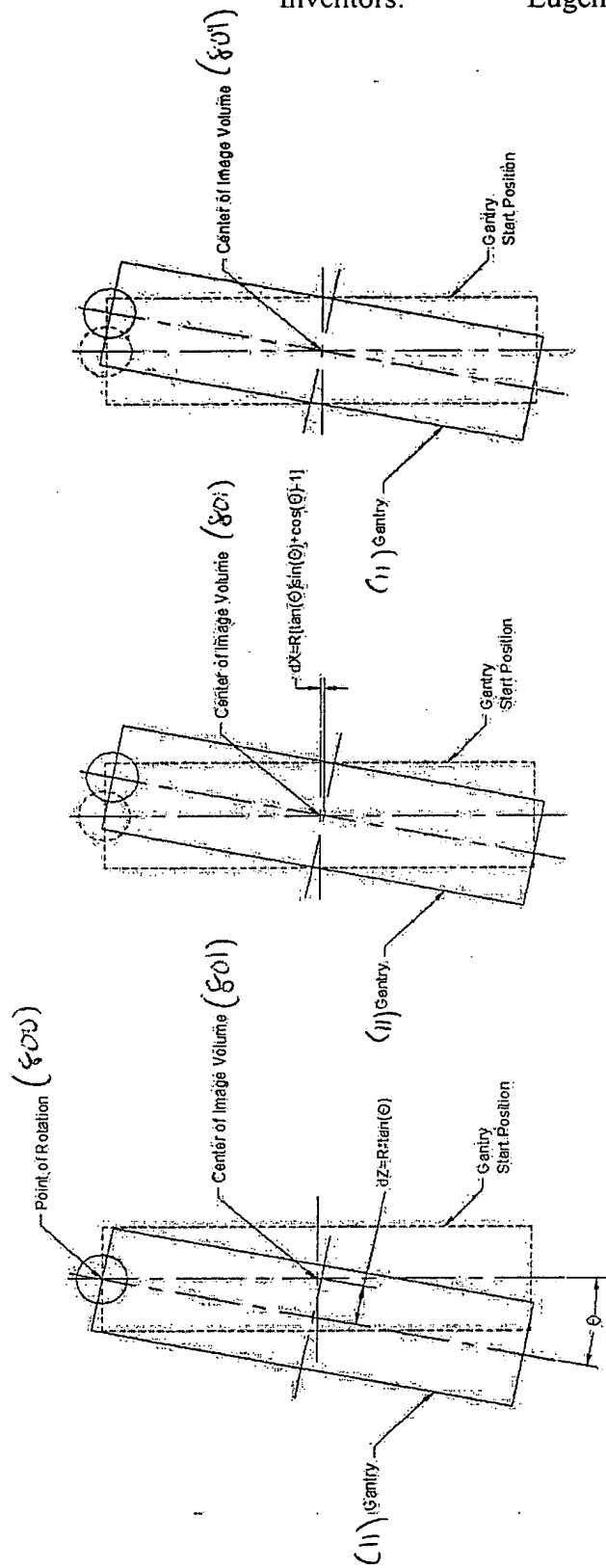


Fig. 7C



Rotate Θ

Translate dZ

Translate dX

Fig. 8A

Fig. 8B

Fig. 8C

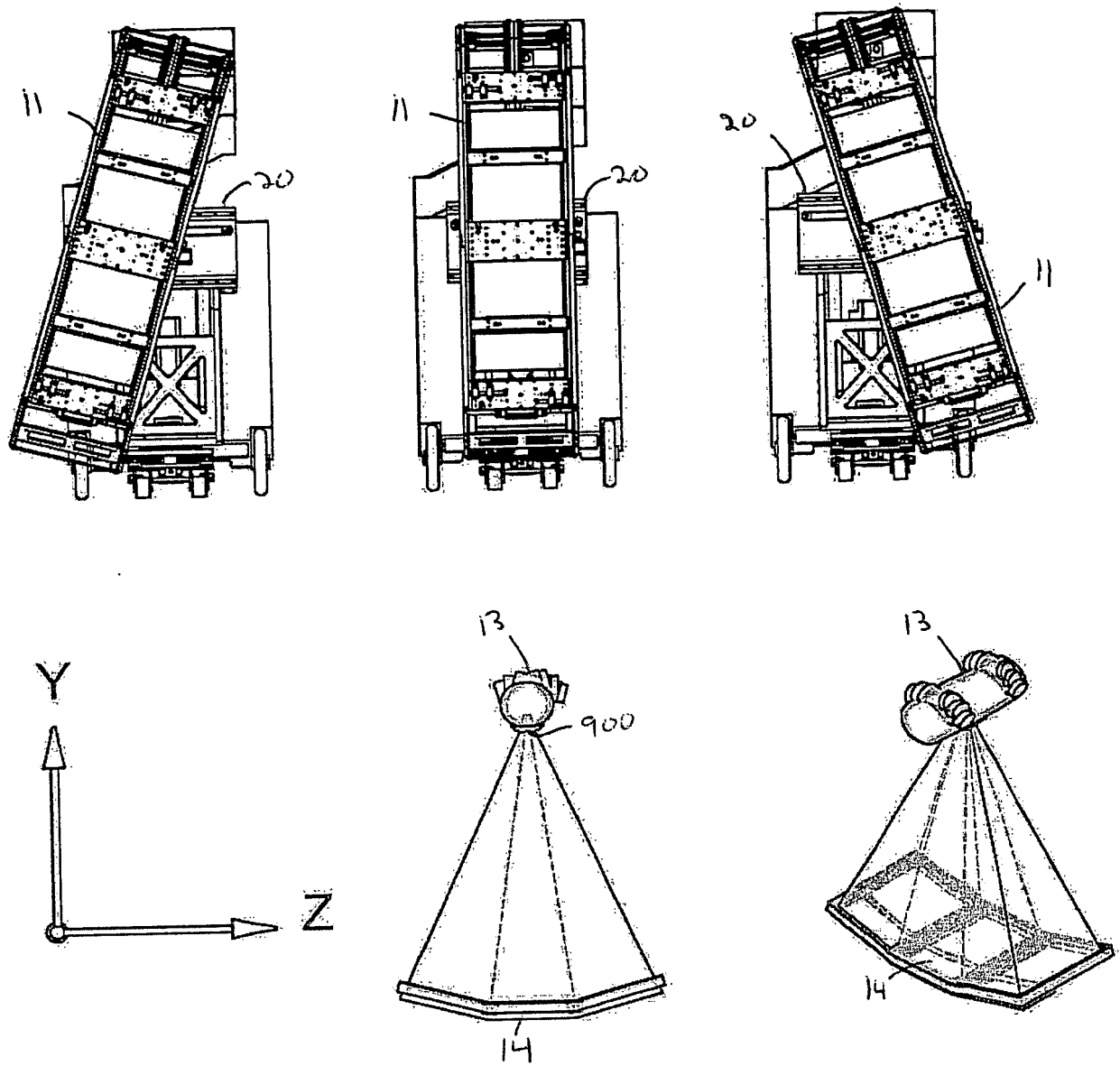


Fig. 9

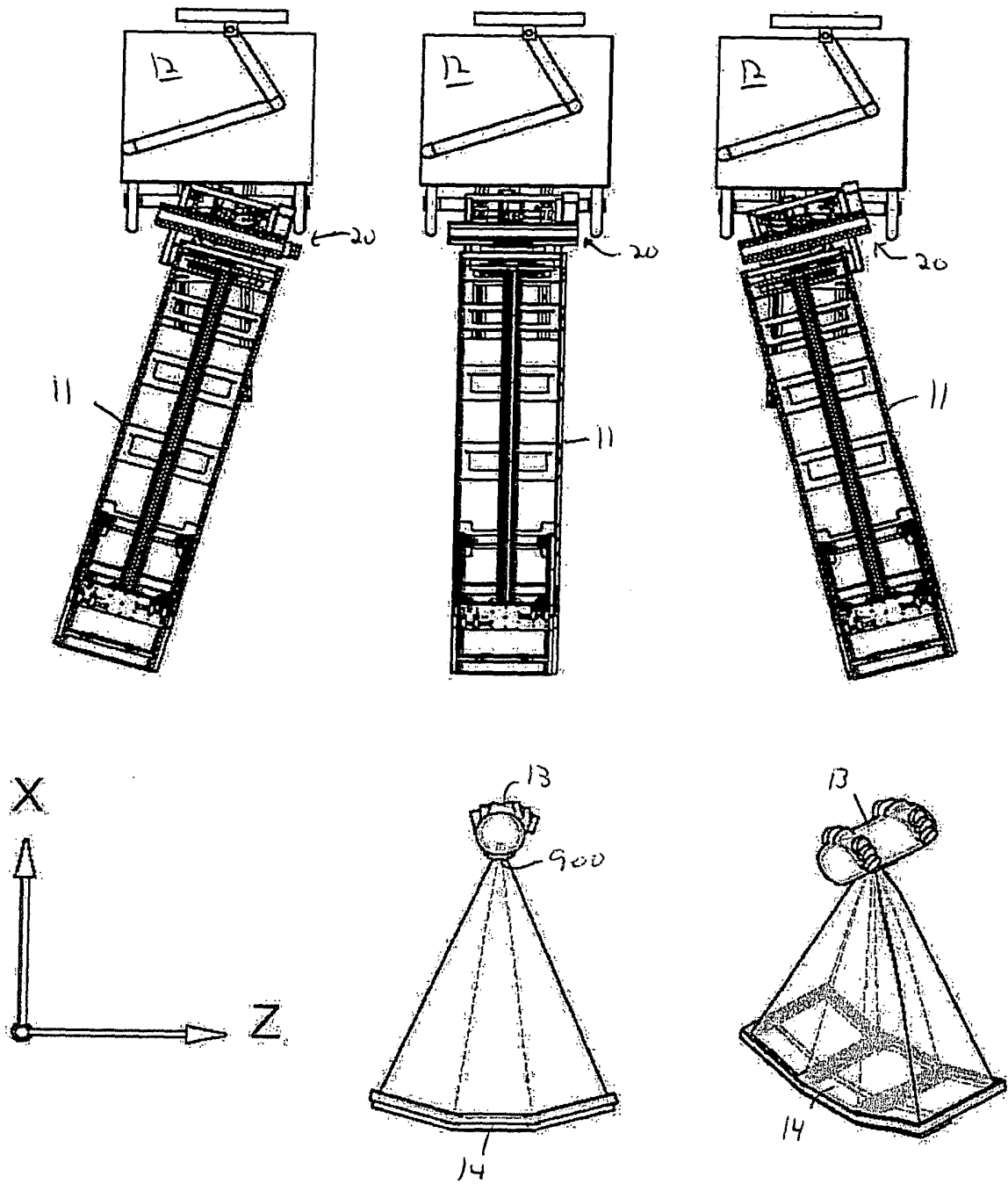


Fig. 10

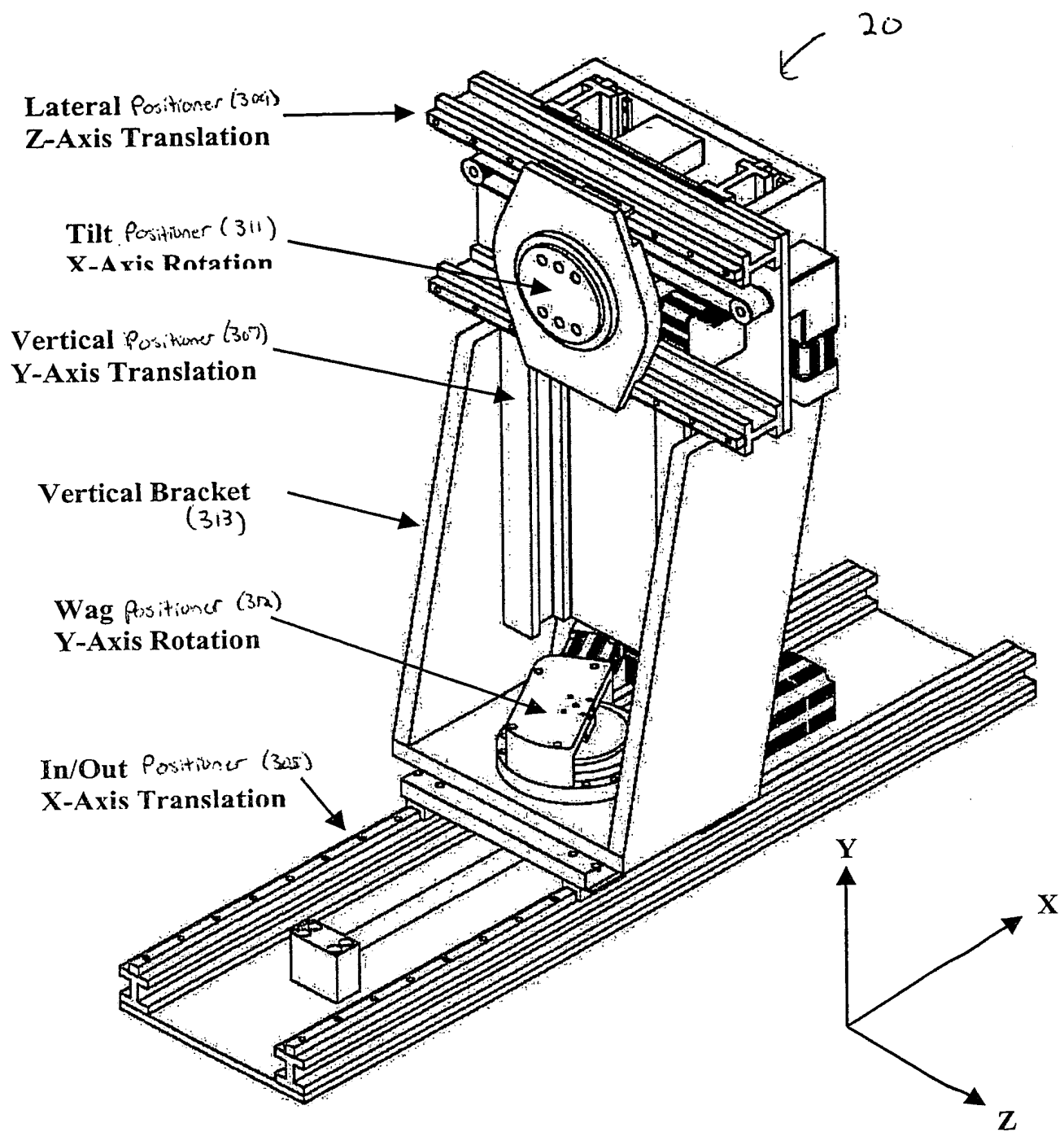


Fig. 11

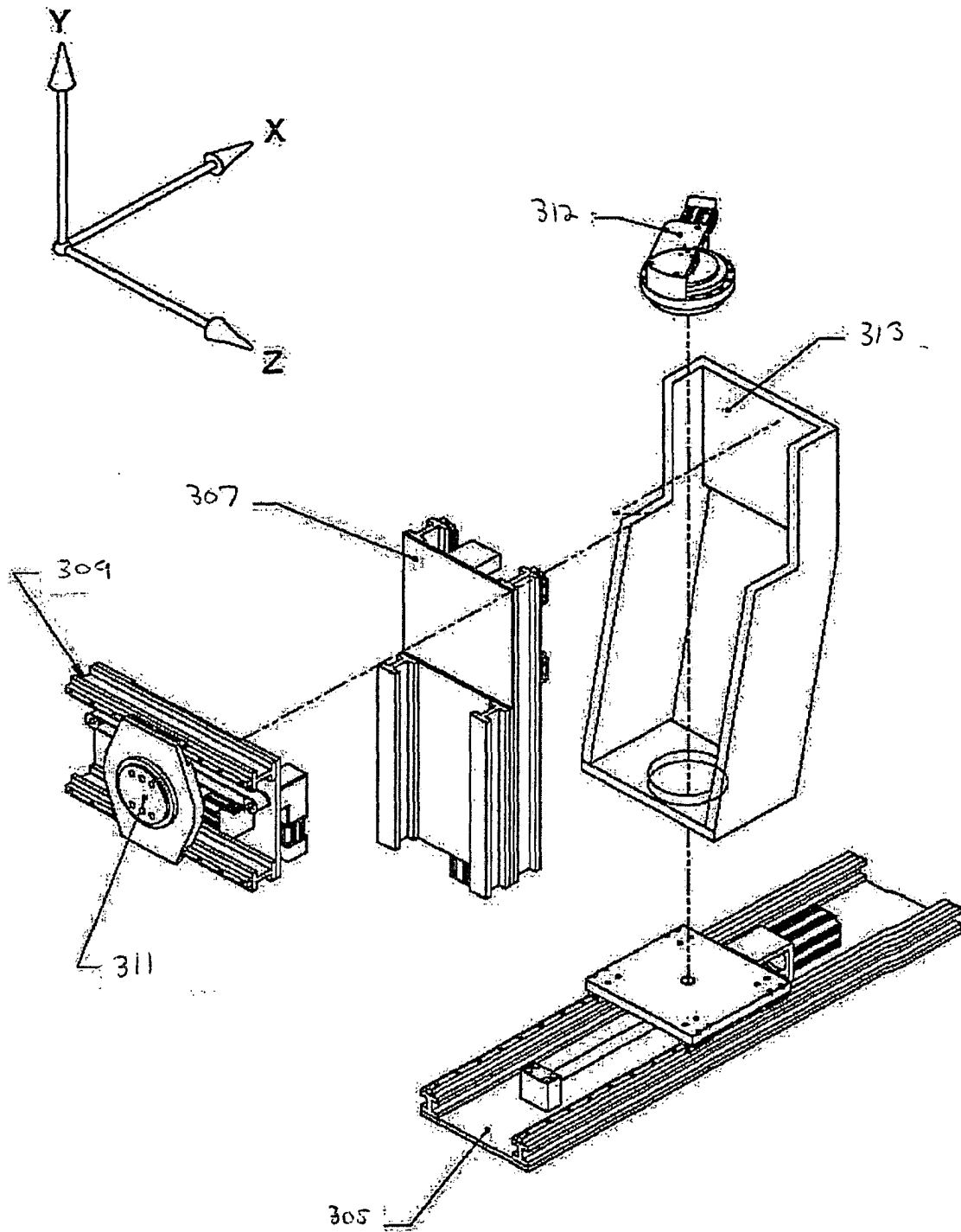


Fig. 12

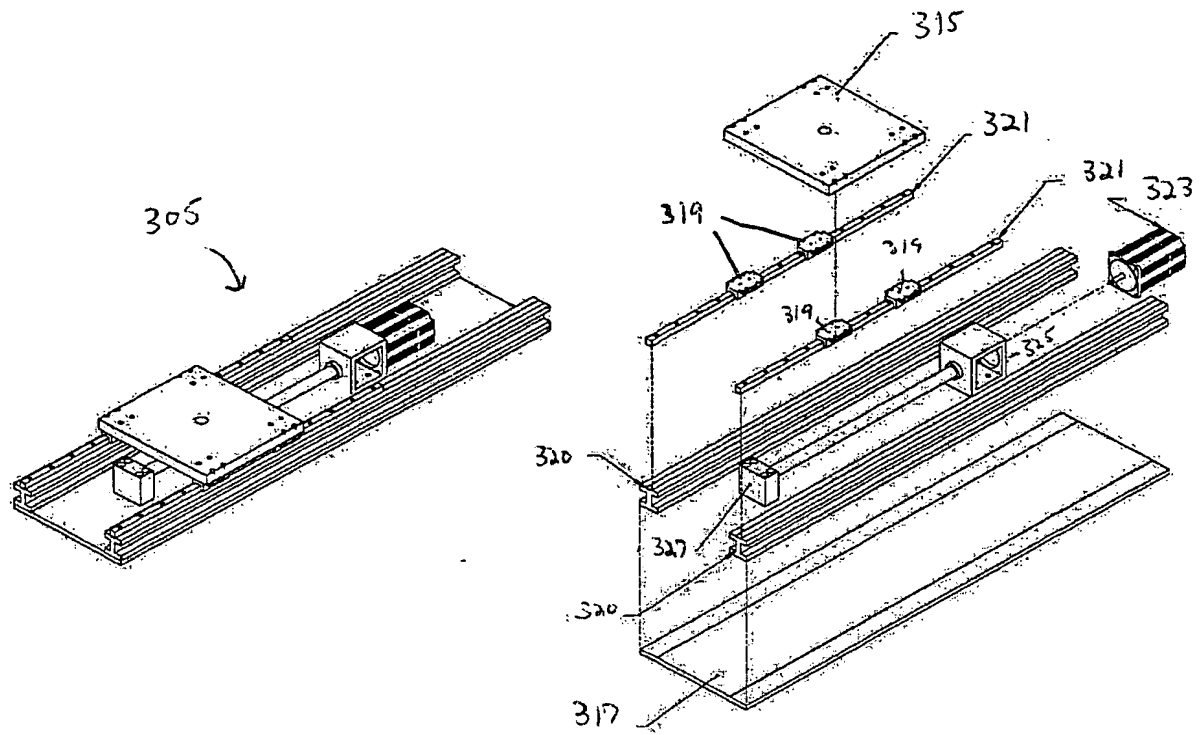


Fig. 13

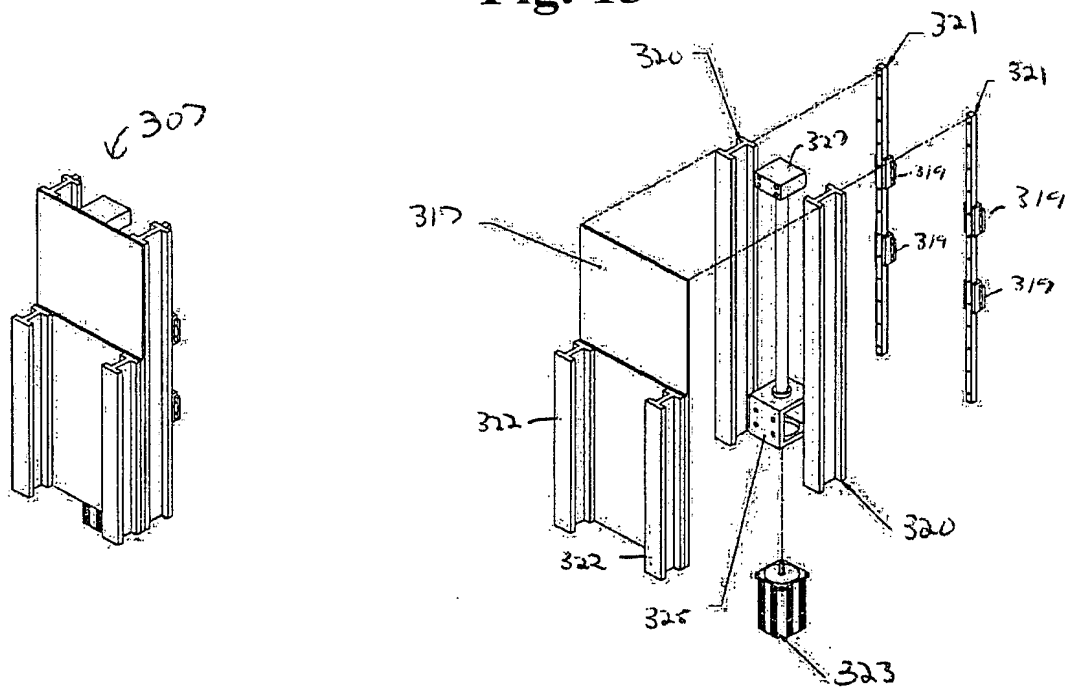


Fig. 14

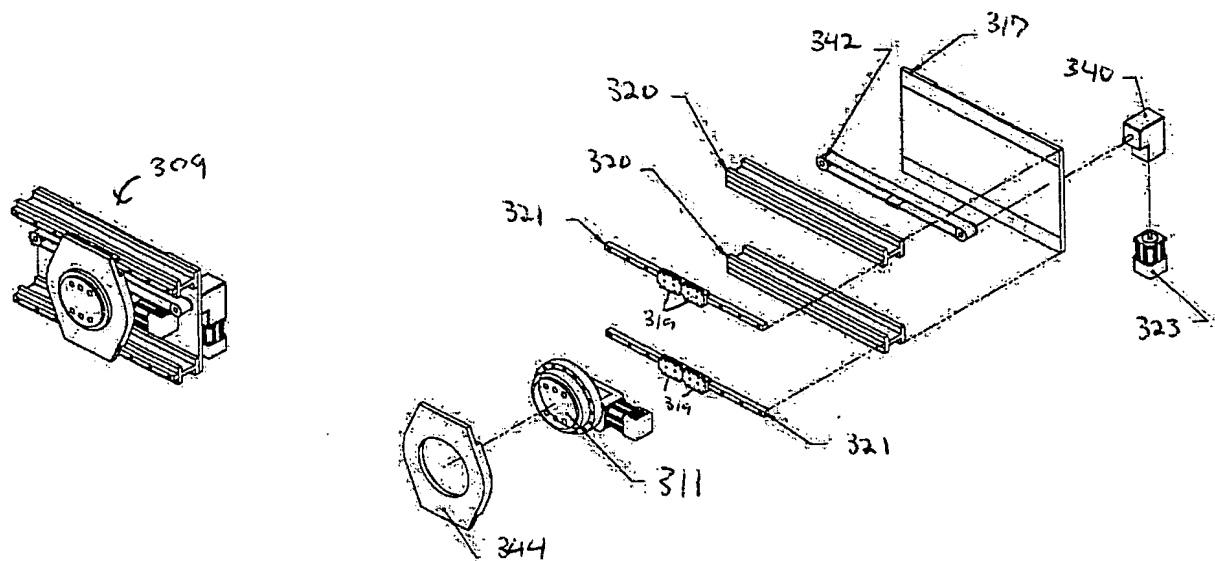


Fig. 15

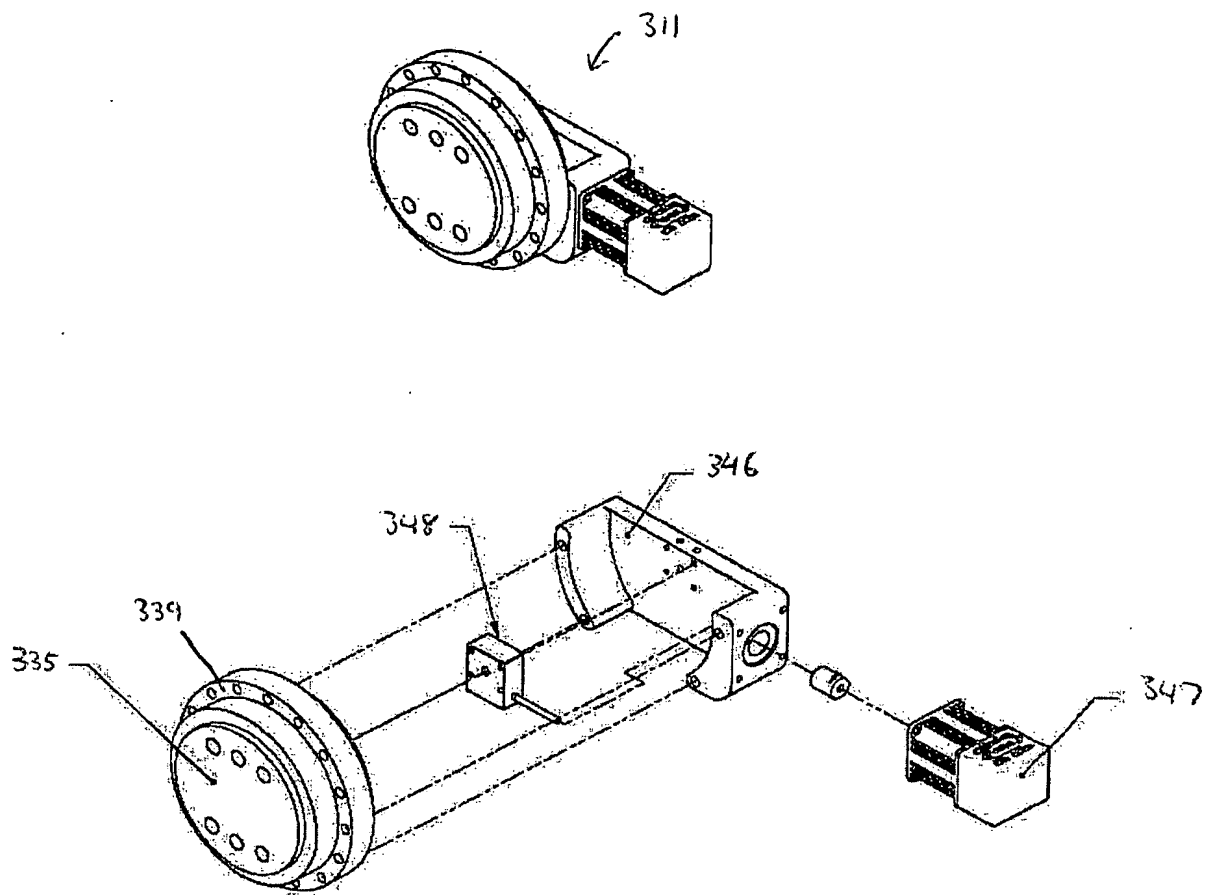


Fig. 16

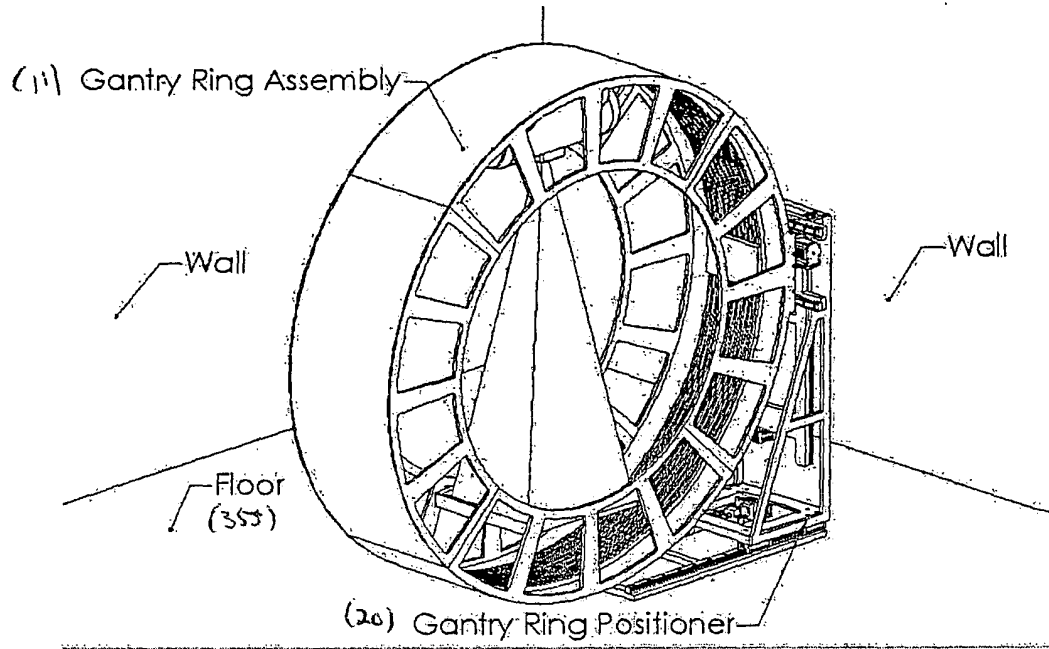


Fig. 17

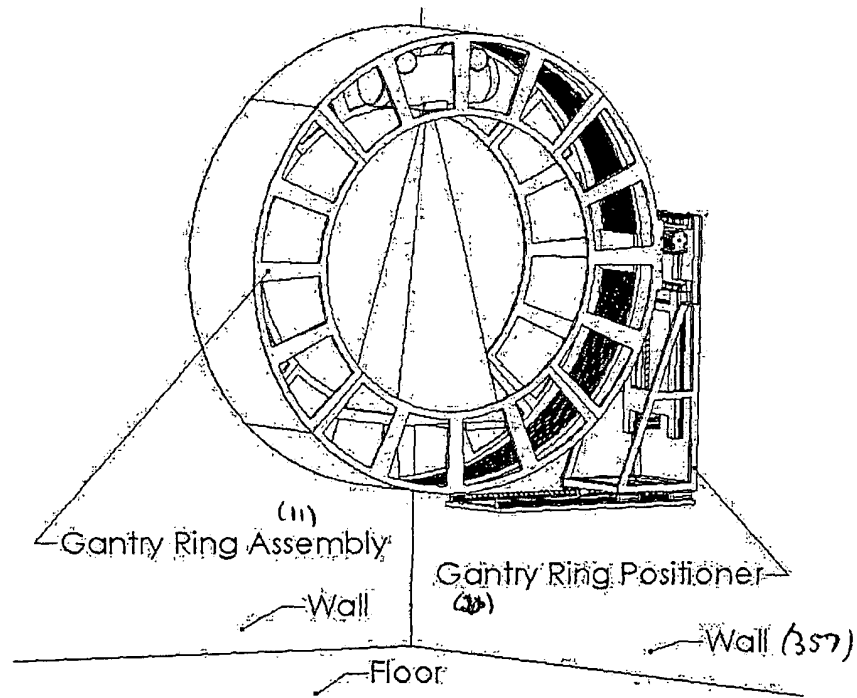


Fig. 18

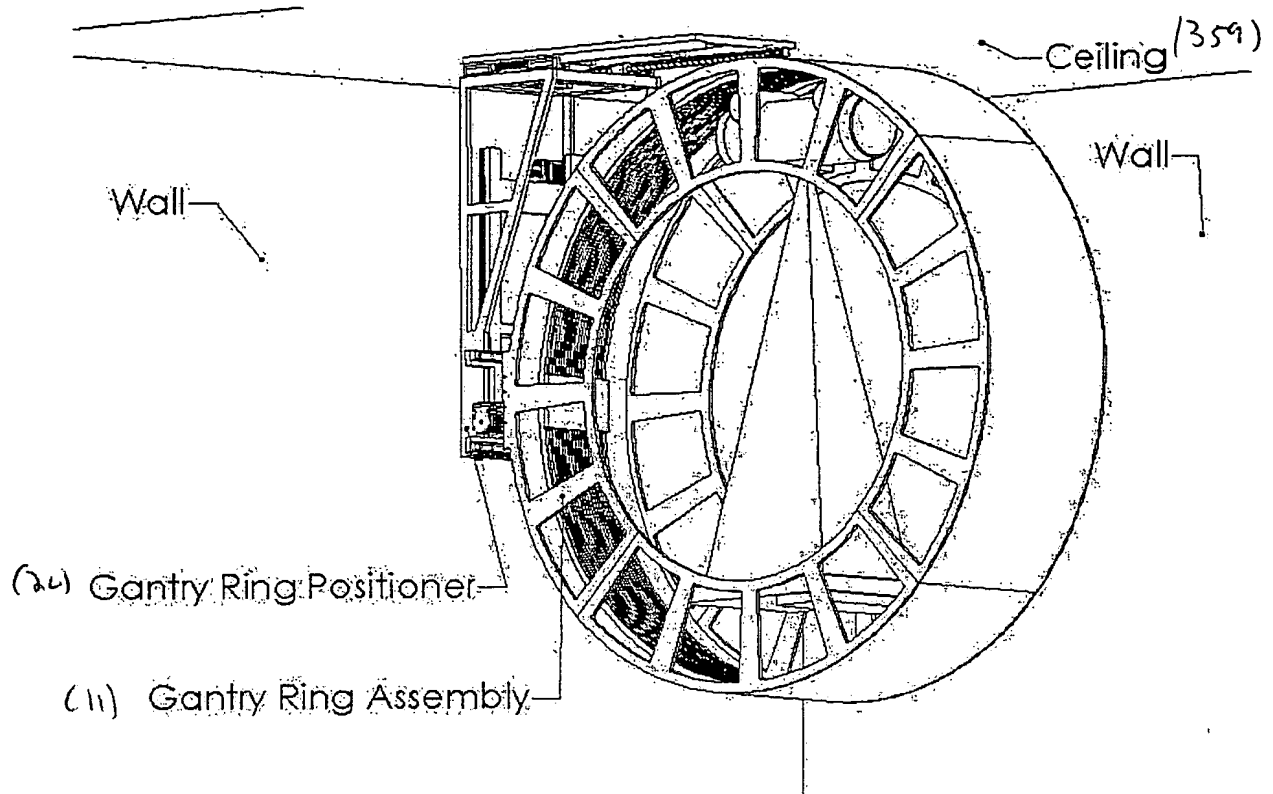


Fig. 19

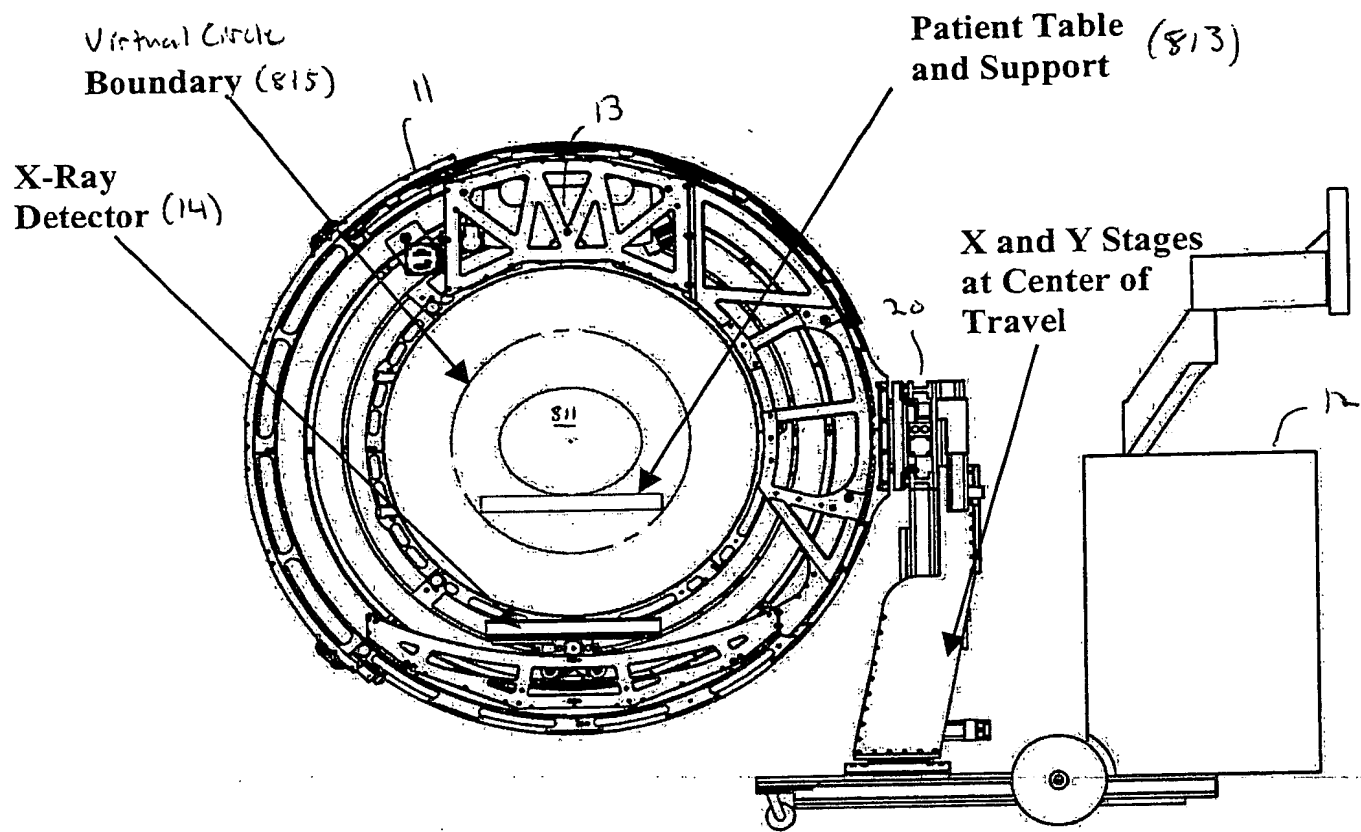


Fig. 20

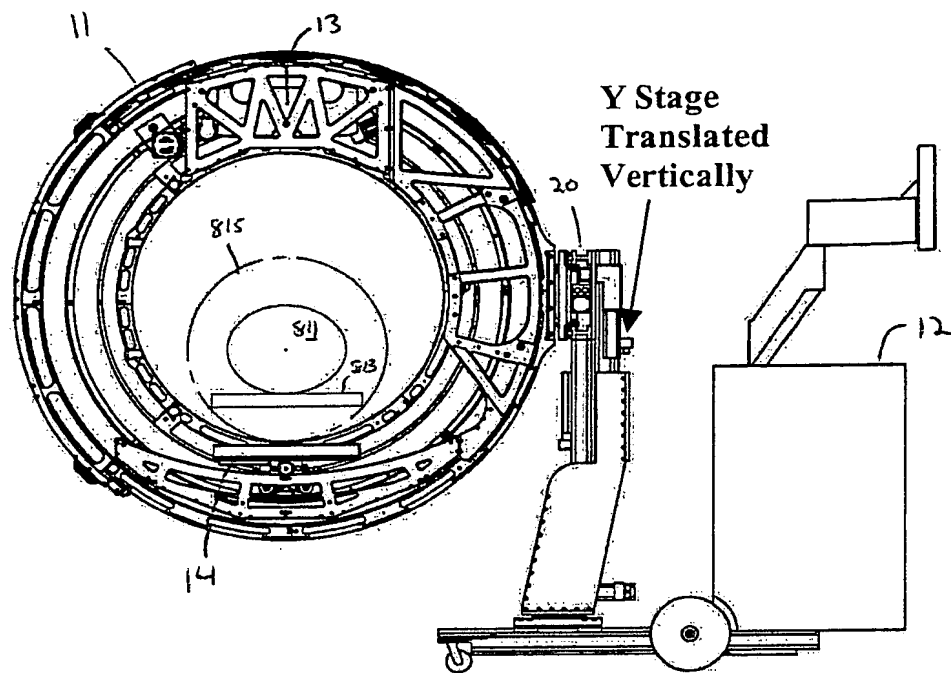


Fig. 21

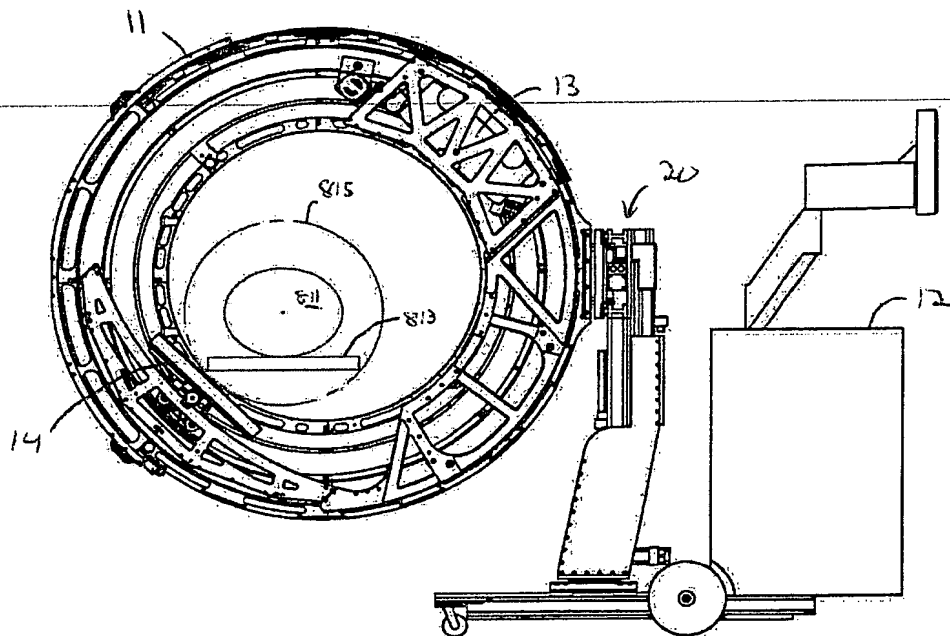


Fig. 22

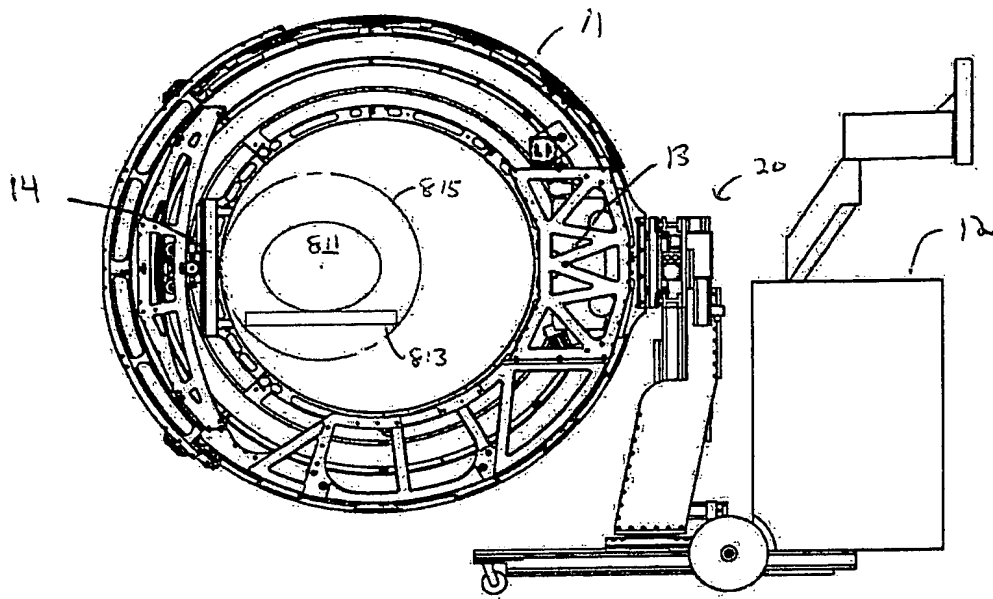


Fig. 23

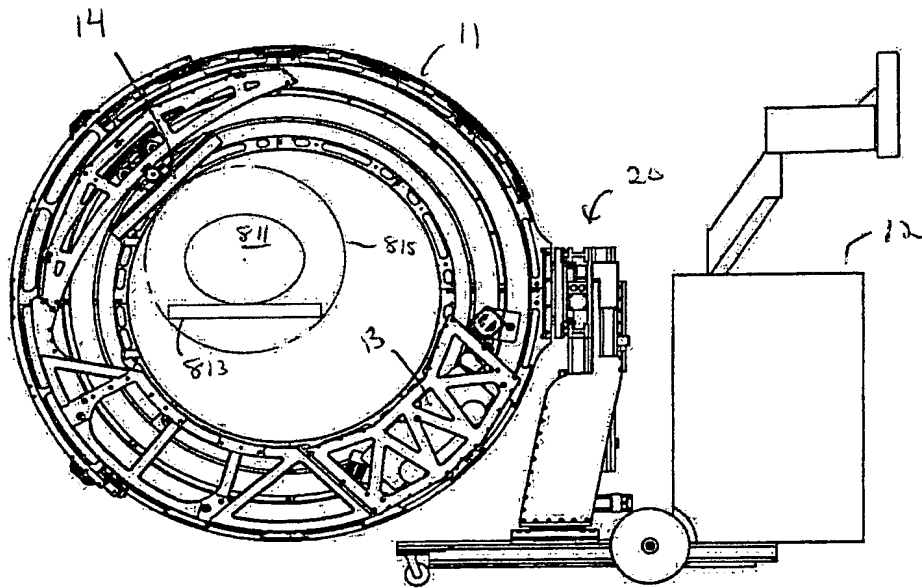


Fig. 24

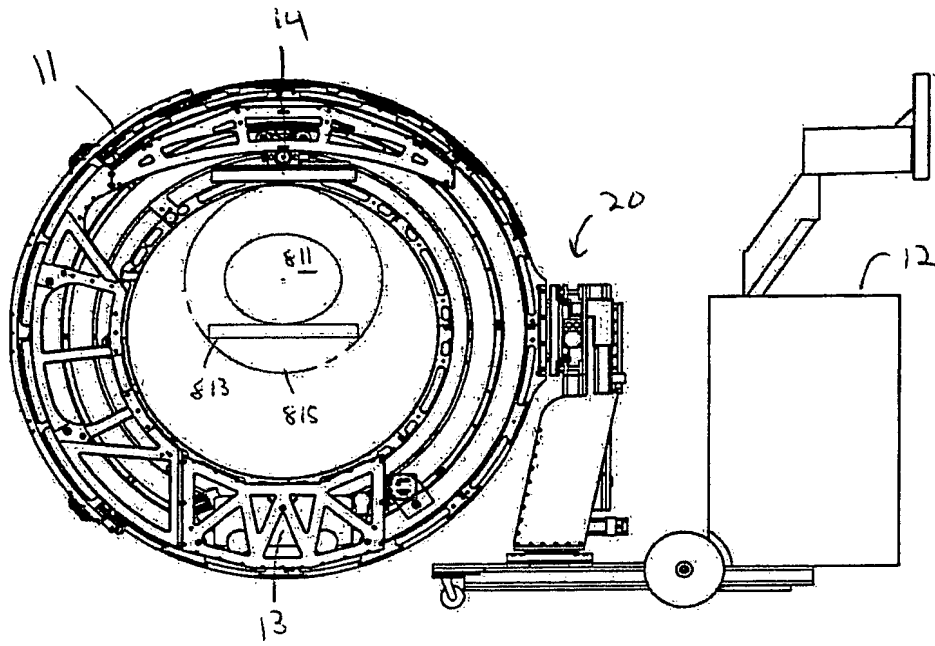


Fig. 25

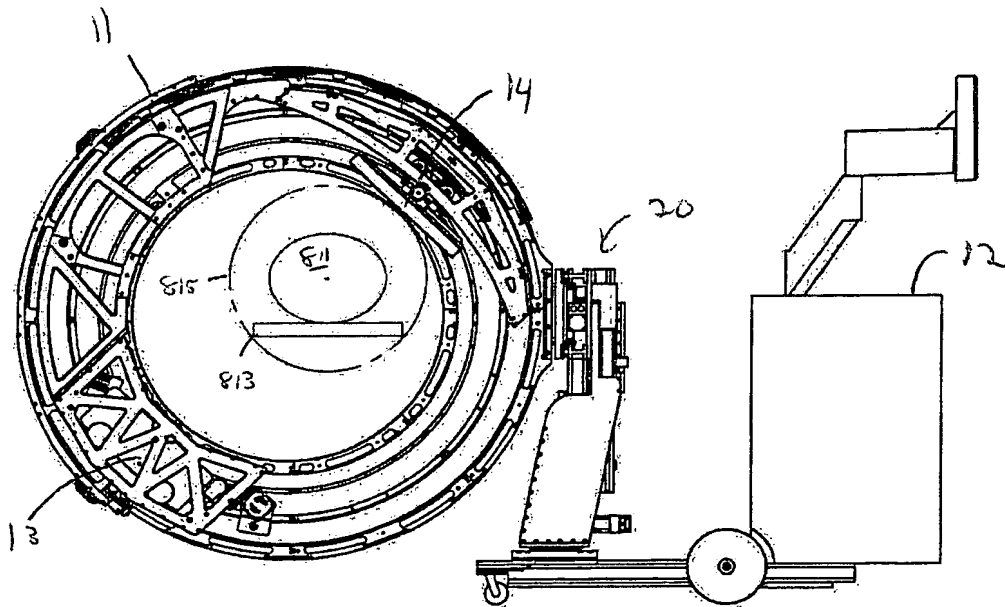


Fig. 26

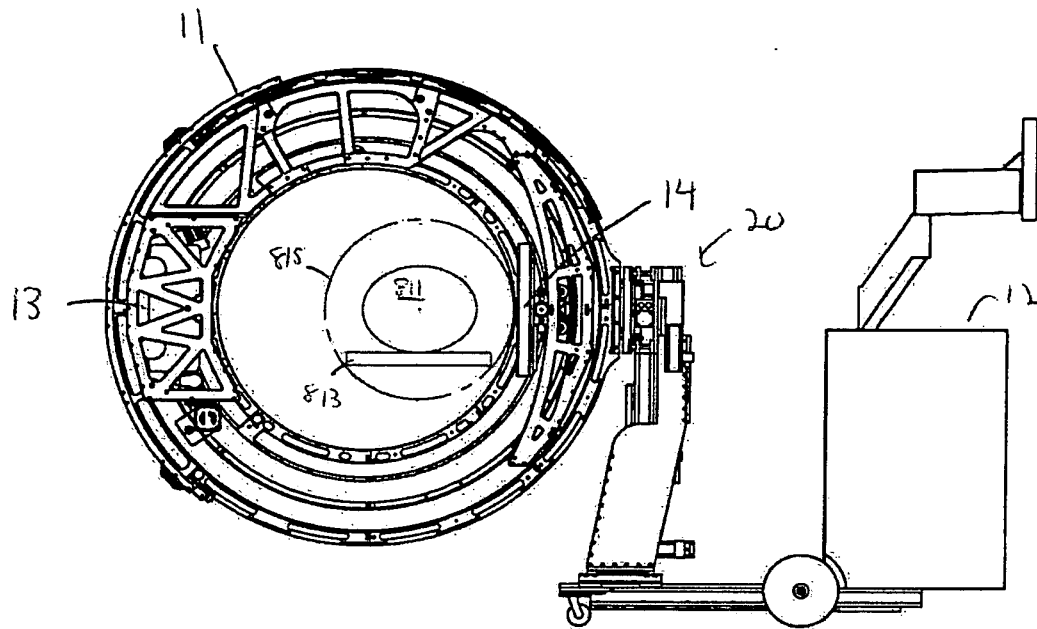


Fig. 27

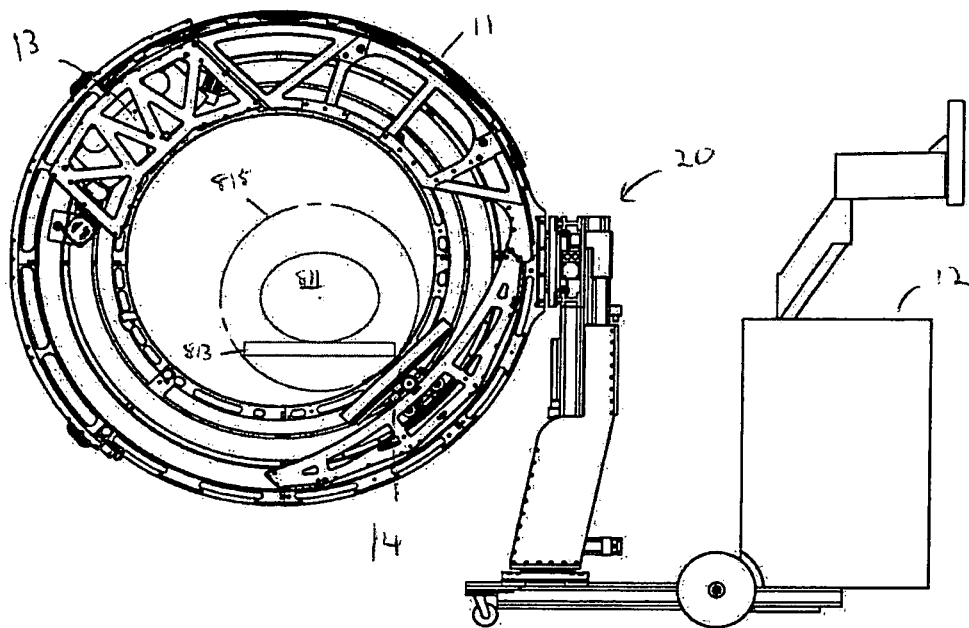


Fig. 28

